## Extension of coastal oceanography to polar environmental sciences 연안해양 연구의 극지 해양환경 연구로의 확장

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## EFML @ KAIST

- Prof. Sung Yong Kim (김 성용)
- Education
  - Ph.D. in Oceanography, Scripps Institution of Oceanography (SIO)/UC San Diego (2009)
  - B.S. in Naval Architecture and Ocean Engineering, Seoul National University (1999)
- Research Interests
  - Air-sea and air-sea-land interactions
  - Mesoscale and submesoscale eddies
  - Environmental sensing using acoustic and electromagnetic sensors
  - Environmental big data analysis and mining
  - Coastal oceanography and environmental hydrodynamic models (ROMS, MITgcm, Delft3d)
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#### **Classic ways to study ocean physics**

- Experimental and theoretical studies
- Numerical simulations
- Observations

"The chief source of ideas in oceanography comes, I think, from new observations... On the whole, when it comes to the phenomenology of the ocean, there are more discoveries than predictions. Most theories are about observations that have already been made." - Henry Stommel (NAS 1959; National Medal of Science)



## **Coastal ocean observing system (COOS)**



## **Ocean sensing and BIG data**











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#### **Boundary layer flows:** At air-sea-land interfaces



#### Submesoscale processes

- O(1) Rossby number [Ro = ζ/f]
- A horizontal scale smaller than the first baroclinic Rossby deformation radius; O(1-10) km
- Frequently observed as fronts, eddies, and filaments
   12km resolution



Simulations on mesoscale and submesoscale grids (SST)

#### Submesoscale processes

- O(1) Rossby number [Ro =  $\zeta/f$ ]
- A horizontal scale smaller than the first baroclinic Rossby deformation radius; O(1-10) km
- Frequently observed as fronts, eddies, and filaments
- Contribute to the vertical transport of oceanic tracers, mass, and buoyancy and rectify the mixed-layer structure and upper-ocean stratification
  - e.g., vertical frontal scale secondary circulation



#### **Remote sensing** – High-frequency radars





#### **Remote sensing – Geostationary Ocean Color Imagery**



#### (0.5 km and hourly; GOCI @ KOSC)

#### Submesoscale process studies

 have benefited from primarily idealized numerical models and theoretical frameworks because they require the use of highresolution observations of less than one hour in time and O(1-10) km in space.



#### How can we identify a system?



# sys.tem

noun

- 1. a set of connected things or parts forming a complex whole, in particular.
- a set of principles or procedures according to which something is done; an organized scheme or method.

"a multiparty system of government"

synonyms: method, methodology, technique, process, procedure, approach, practice; More





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How can we identify a system?

Governing equations







How can we identify a system?



- A statistical relationship between inputs and outputs
  - Transfer function or response function

$$\hat{\mathbf{u}}(z,\omega) = \mathbf{H}(z,\omega)\hat{\boldsymbol{\tau}}(\omega)$$
  $\mathbf{u}(z,t) = \int_{t'} \mathbf{G}(z,t-t')\boldsymbol{\tau}(t') \,\mathrm{d}t',$ 

Examples of a linear 'ocean' system using two approaches

#### Isotropic ocean responses

 "In the Northern Hemisphere, the wind-driven current at the very surface will be directed 45° to the right of the wind direction." (Phys. Oceanogr. 101; Ekman 1905)



#### Linearized (momentum) equations – isotropic case

$$\begin{aligned} \frac{\partial u}{\partial t} - f_c v &= \frac{1}{\rho} \frac{1}{\partial z} \left( \mu \frac{\partial u}{\partial z} \right) \\ \frac{\partial v}{\partial t} + f_c u &= \frac{1}{\rho} \frac{1}{\partial z} \left( \mu \frac{\partial v}{\partial z} \right) \end{aligned}$$

$$[\mathbf{u} = u + iv \ [\boldsymbol{ au} = au_x + i au_y]]$$

Then, Fourier transform

$$\lambda^2 \mathbf{\hat{u}}(z,\omega) = \frac{\partial^2 \mathbf{\hat{u}}(z,\omega)}{\partial z^2},$$

where 
$$\lambda = \sqrt{i(\omega + f_c) / \nu}$$
,

 $\nu$  = Depth independent eddy viscosity

#### With BCs (finite or infinite depth)

$$\frac{\partial \hat{\mathbf{u}}(z,\omega)}{\partial z}\Big|_{z=0} = \frac{\hat{\boldsymbol{\tau}}(\omega)}{\rho\nu}. \qquad \hat{\mathbf{u}}(z,\omega)|_{z=-\infty} = 0,$$
$$\mathbf{H}(z,\omega) = \frac{\hat{\mathbf{u}}(z,\omega)}{\hat{\boldsymbol{\tau}}(\omega)} = \frac{e^{-\lambda z}}{\lambda\rho\nu},$$

(Gonella, DSR 1972)

#### Wind-current relationship at 32°N



(Kim et al, JPO 2009)

#### Statistical linear relationship

- A statistical framework to represent the link between wind and currents in the frequency and time domains.
- Isotropic analyses and models.

$$\hat{\tau}(\omega) \Rightarrow \mathbf{H}(\omega) \Rightarrow \hat{\mathbf{u}}(\omega)$$

$$\tau(t) \Rightarrow \mathbf{G}(t-t') \Rightarrow \mathbf{u}(t)$$

$$\mathbf{rransfer function}$$

$$\hat{\mathbf{u}}(z,\omega) = \mathbf{H}(z,\omega)\hat{\tau}(\omega)$$

$$\mathbf{H}(z,\omega) = \left(\langle \hat{\mathbf{u}}(z,\omega) \, \hat{\tau}^{\dagger}(\omega) \rangle\right) \left(\langle \hat{\tau}(\omega) \, \hat{\tau}^{\dagger}(\omega) \rangle + \mathbf{R}_{\mathbf{a}} \right)^{-1}$$

$$\mathbf{R}_{\mathbf{a}} : \text{Regularization matrix}$$

$$\tau(t) \Rightarrow \mathbf{G}(t-t') \Rightarrow \mathbf{u}(t)$$

$$\mathbf{Response function}$$

$$\mathbf{u}(z,t) = \int_{t'} \mathbf{G}(z,t-t') \tau(t') \, \mathrm{d}t',$$

$$\mathbf{G}(z,t) = \left(\langle \mathbf{u}(z,t) \, \tau_{N}^{\dagger}(t) \rangle\right) \left(\langle \tau_{N}(t) \, \tau_{N}^{\dagger}(t) \rangle + \mathbf{R}_{\mathbf{b}} \right)^{-1}$$

$$\tau_{N}: N-\text{hour advanced time lagged wind stress}$$

$$\mathbf{R}_{\mathbf{b}}: \text{Regularization matrix}$$

#### Wind transfer function and response function



#### **Long-term data analysis** – CTD data w/ season and climate indices



#### Long-term data analysis – sea ice coverage w/ AOI

Spatial Coverage of Sea ice, 1987-2013



